

Last Time. We started discussing Stokes' theorem:

$$\int_{\partial D} \alpha = \int_D d\alpha$$

for a regular domain D with boundary ∂D in an oriented manifold M and a compactly supported form α of degree $\dim M - 1$.

Today we will make sense of the “d” in “d α ” in the statement of Stokes' theorem above. Later we will define regular domains, their boundaries and orientation of boundaries induced by the orientation of the ambient manifold.

Theorem 29.1 (Exterior Derivative). *For every manifold M there is a unique \mathbb{R} -linear map*

$$d_M : \Omega^*(M) \rightarrow \Omega^{*+1}(M)$$

(i.e. $\forall \omega \in \Omega^k(M)$ we have $d_M \omega \in \Omega^{k+1}(M)$) called exterior derivative such that

- (1) For all $f \in C^\infty = \Omega^0(M)$ we have $d_M f = df$.
- (2) For all open $W \subseteq M$ and all $\omega \in \Omega^k(M)$ we have $(d_M \omega)|_W = d_W(\omega|_W)$
- (3) For all $\omega \in \Omega^k(M)$ and all $\eta \in \Omega^l(M)$ we have $d_M(\omega \wedge \eta) = d_M(\omega) \wedge \eta + (-1)^k \omega \wedge d_M \eta$
- (4) For all $\omega \in \Omega^k(M)$ we have $d_M(d_M \omega) = 0$ (i.e. $d_M^2 = 0$).

Proof of Uniqueness. Suppose that there exists $d_M : \Omega^*(M) \rightarrow \Omega^{*+1}(M)$ with properties (1)-(4) above. Let $(x_1, \dots, x_m) : U \rightarrow \mathbb{R}^m$ be a coordinate chart. Then for all $\alpha \in \Omega^k(M)$

$$\alpha|_U = \sum_{|I|=k} a_I dx_I = \sum_{I=i_1 < \dots < i_k} a_I dx_{i_1} \wedge \dots \wedge dx_{i_k}$$

Claim 1. *If d exists then we must have $d_U(dx_I) = 0$*

Proof. We will proceed by induction on k . If $k = 1$ then

$$d_U(dx_{i_1}) \stackrel{\text{by(1)}}{=} d_U d_U x_{i_1} \stackrel{\text{by(4)}}{=} 0.$$

Suppose that $d_U(dx_{i_1} \wedge \dots \wedge dx_{i_n}) = 0$, then

$$d_U(dx_{i_1} \wedge \dots \wedge dx_{i_n} \wedge dx_{i_{n+1}}) \stackrel{\text{by(3)}}{=} d_U(dx_{i_1} \wedge \dots \wedge dx_{i_n}) \wedge dx_{i_{n+1}} + (-1)^n dx_{i_1} \wedge \dots \wedge dx_{i_n} \wedge d_U(dx_{i_{n+1}}).$$

Hence

$$\begin{aligned} (d_M \alpha)|_U &= d_U(\alpha|_U) \\ &= d_U \left(\sum_{|I|=k} a_I dx_I \right) \\ &= \sum_{|I|=k} (d_U a_I \wedge dx_I + a_I d_U(dx_I)) \\ &= \sum_{|I|=k} da_I \wedge dx_I. \end{aligned}$$

Therefore if $d'_M \Omega^*(M) \rightarrow \Omega^{*+1}(M)$ is another \mathbb{R} -linear map with properties (1)-(4), then for all k , all $\alpha \in \Omega^k(M)$, and all coordinate charts U we have

$$(d'_M \alpha)|_U = d'_U(\alpha|_U) = d'_U \left(\sum a_I dx_I \right) = \sum da_I \wedge dx_I = (d_M \alpha)|_U.$$

This proves uniqueness of the exterior derivative d_M . □

Proof of Existence. For each coordinate chart $(x_1, \dots, x_m) : U \rightarrow \mathbb{R}^m$ on M define for all k the map $d_U : \Omega^k(M) \rightarrow \Omega^{k+1}(M)$ by

$$(29.1) \quad d_U \left(\sum_{|I|=k} a_I dx_I \right) \stackrel{\text{def}}{=} \begin{cases} da_I & \text{if } |I| = 0 \\ \sum_{|I|=k} da_I \wedge dx_I & \text{if } |I| > 0 \end{cases}$$

Assume for the moment:

Claim 2. d_U defined by (29.1) has properties (1)-(4).

Now define $d_M : \Omega^*(M) \rightarrow \Omega^{*+1}(M)$ as follows: for any coordinate chart U set

$$(29.2) \quad (d_M \alpha)|_U = d_U(\alpha|_U)$$

Does equation 29.2 make sense? Suppose that U and V are two compatible coordinate charts. Then

$$\begin{aligned} (d_U(\alpha|_U))|_{U \cap V} &\stackrel{\text{Claim (2)}}{=} d_{U \cap V}(\alpha|_U|_{U \cap V}) \\ &= d_{U \cap V}(\alpha|_V|_{U \cap V}) \\ &\stackrel{\text{Claim (2)}}{=} (d_U(\alpha|_V))|_{U \cap V} \end{aligned}$$

Next we prove claim 2. We check conditions (1)-(4).

(1). For all $f \in C^\infty(U)$ we have $d_U f = df$ by definition of d_U .

(2). Recall that we proved that d commutes with pullbacks and restriction $|_W$ to W is the pullback by the inclusion $W \hookrightarrow U$. Hence for any $f \in C^\infty(U)$ and any open $W \subseteq U$ we have

$$(d_U f)|_W = df|_W = d(f|_W) = d_W(f|_W)$$

Now

$$\begin{aligned} d_U(a_I dx_I)|_W &= (da_I \wedge dx_I)|_W \\ &= da_I|_W \wedge (dx_I)|_W \\ &= d(a_I|_W) \wedge d(dx_I|_W) \\ &= d_W((a_I dx_I)|_W) \end{aligned}$$

Hence d_U has property (2).

(3). It is no loss of generality to assume that $\omega = a_I dx_I$ and $\eta = b_J dx_J$ for some indices I and J and some functions a_I, b_J . Then

$$\begin{aligned} d_U(\omega \wedge \eta) &= d_U(a_I dx_I \wedge b_J dx_J) \\ &= d_U(a_I b_J dx_I \wedge dx_J) \\ &= da_I b_J \wedge dx_I \wedge dx_J \\ &= \underbrace{da_I \wedge dx_I}_{d\omega} \wedge \underbrace{b_J dx_J}_{\eta} + (-1)^k \underbrace{a_I dx_I}_{\omega} \wedge \underbrace{db_J \wedge dx_J}_{d\eta} \end{aligned}$$

This proves that (3) holds for d_U .

(4).

$$\begin{aligned} d_U(d_U(a_I dx_I)) &= d_U(da_I \wedge dx_I) \\ &= d_U(da_I) \wedge dx_I + (-1)^k da_I \wedge \underbrace{d_U(dx_I)}_{=0} \\ &= d_U\left(\sum \frac{\partial a_I}{\partial x_i} dx_i\right) \wedge dx_I \end{aligned}$$

Now

$$d_U\left(\sum \frac{\partial a_I}{\partial x_i} dx_i\right) = \sum_{i,j} \underbrace{\frac{\partial^2 a_I}{\partial x_i \partial x_j}}_{\text{Symmetric}} \underbrace{dx_j \wedge dx_i}_{\text{Skew-symmetric}},$$

hence is 0. Therefore $d_U(d_U(a_I dx_I)) = 0$ and consequently $d_U \circ d_U = 0$. This proves claim 2. \square

It remains to show that d_M defined by equation 29.2 has properties (1)-(4).

(1). For all $f \in C^\infty(M)$ and any coordinate chart U

$$(d_M f)|_U \stackrel{\text{by our definition of } d_M}{=} d_U(f|_U) = d(f|_U) = df|_U.$$

Since U is arbitrary, $d_M f = df$.

(2). For all open $W \subseteq M$ and all coordinate charts $U \subseteq M$ we know that $U \cap W$ is a coordinate chart on W . Since d_U has property (3), we know that for all $\mu \in \Omega^*(U)$

$$(29.3) \quad (d_U \mu)|_{U \cap W} = d_{U \cap W}(\mu|_{U \cap W})$$

Therefore for any $\omega \in \Omega^*(M)$

$$\begin{aligned} ((d_M \omega)|_W)|_{U \cap W} &= d_M \omega|_{U \cap W} \\ &= ((d_M \omega)|_U)|_{W \cap U} \\ &\stackrel{29.2}{=} (d_U(\omega|_U))|_{W \cap U} \\ &\stackrel{29.3}{=} d_{W \cap U}(\omega|_U|_{W \cap U}) \\ &\stackrel{29.2}{=} d_W(\omega|_W)|_{W \cap U} \end{aligned}$$

Hence $d_M \omega|_W = d_W(\omega|_W)$ if d_M and d_W are defined by equation 29.2.

(3). Say $\omega \in \Omega^k(M)$, $\eta \in \Omega^l(M)$ and U a coordinate chart, then

$$\begin{aligned} d_M(\omega \wedge \eta)|_U &\stackrel{29.2}{=} d_U((\omega \wedge \eta)|_U) \\ &= d_U(\omega|_U \wedge \eta|_U) \\ &= d_U(\omega|_U) \wedge (\eta|_U) + (-1)^k (\omega|_U) \wedge d_U(\eta|_U) \\ &= ((d_M \omega) \wedge \eta)|_U + (-1)^k (\omega \wedge (d_M \eta))|_U \end{aligned}$$

(4).

$$d_M(d_M \omega)|_U = d_U((d_M \omega)|_U) = d_U(d_U(\omega|_U)) = 0$$

since $d_U \circ d_U = 0$.